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# Intro to Keras

— Hello world! —

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# Overview

- How to build your own Neural Network?
- Keras Library.
- First example.
- Exercise: Recognition of handwritten digits.

# How to build your own NN?

## Input X & Output Y

nature (fixed, sequential, ..),  
type, shape

## Architecture

Type of layers, # of layers,  
kernels size, ...

## The task

regression, classification, ...,  
and therefore, your loss  
function.

## Tune hyperparameters

Learning rate, batch size, # of  
epochs, ...

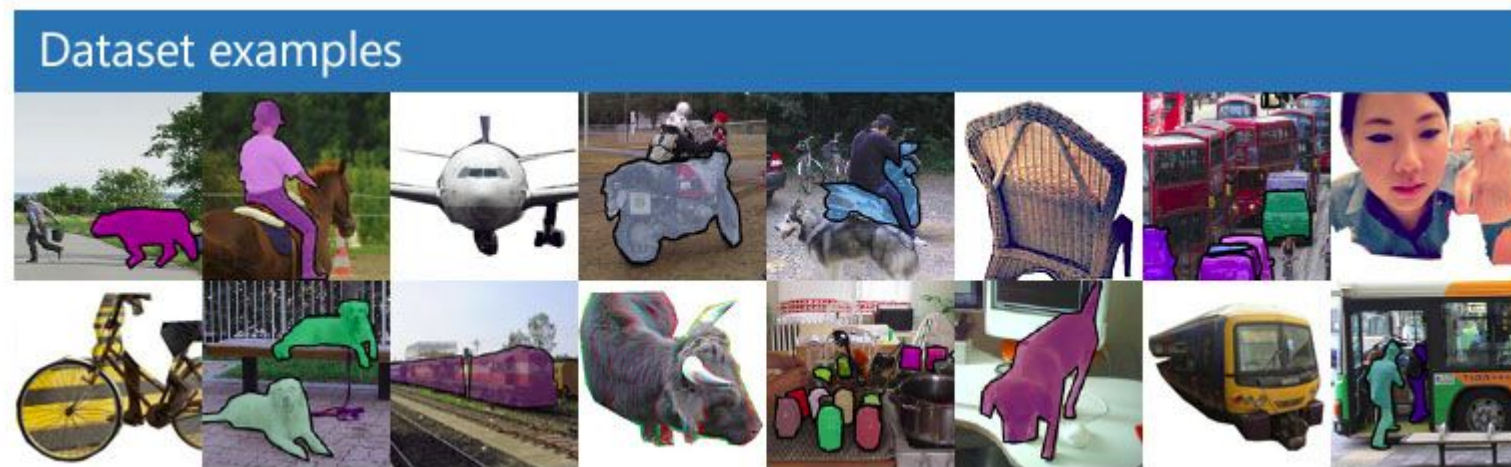
# 1. Specify Input (X) & Output (Y)

- Input:
  - Vector,
  - n-D matrix,
  - sequential data,
  - Multimodal input, ...
- Output:
  - discrete scalar,
  - vector,
  - n-D matrix,
  - sequential output, ...

## 2. Define the task

### A. Classification predictive modeling:

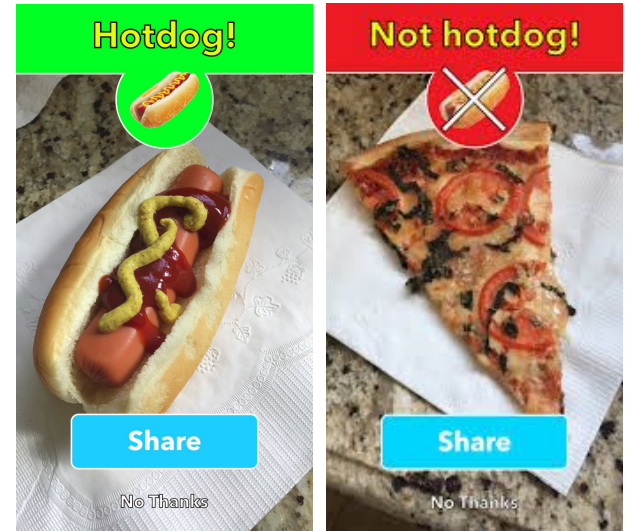
is the task of approximating a mapping function ( $f$ ) from input variables ( $X$ ) to discrete output variables ( $y$ ). The output variables are often called labels or categories. The mapping function predicts the class or category for a given observation.



## 2. Define the task

- A classification problem requires that examples be classified into one of two or more classes.
- A problem with two classes is often called a two-class or **binary classification problem**.
- A problem with more than two classes is often called a **multi-class classification problem**.
- A problem where an example is assigned to multiple classes is called a **multi-label classification problem**.

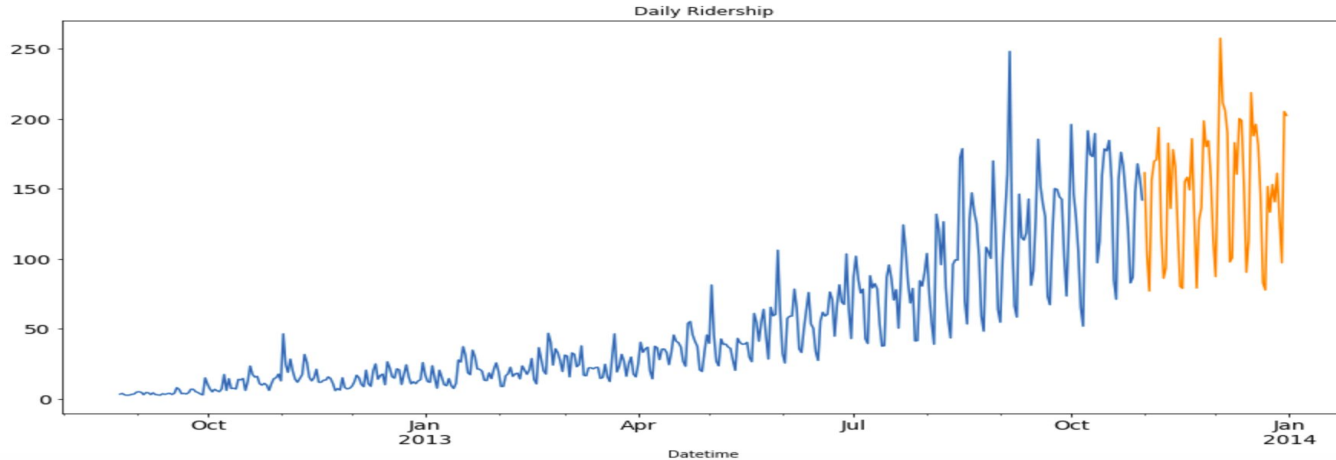
There are many ways to evaluate a classification predictive model, but perhaps the most common is to calculate the classification accuracy.



## 2. Define the task

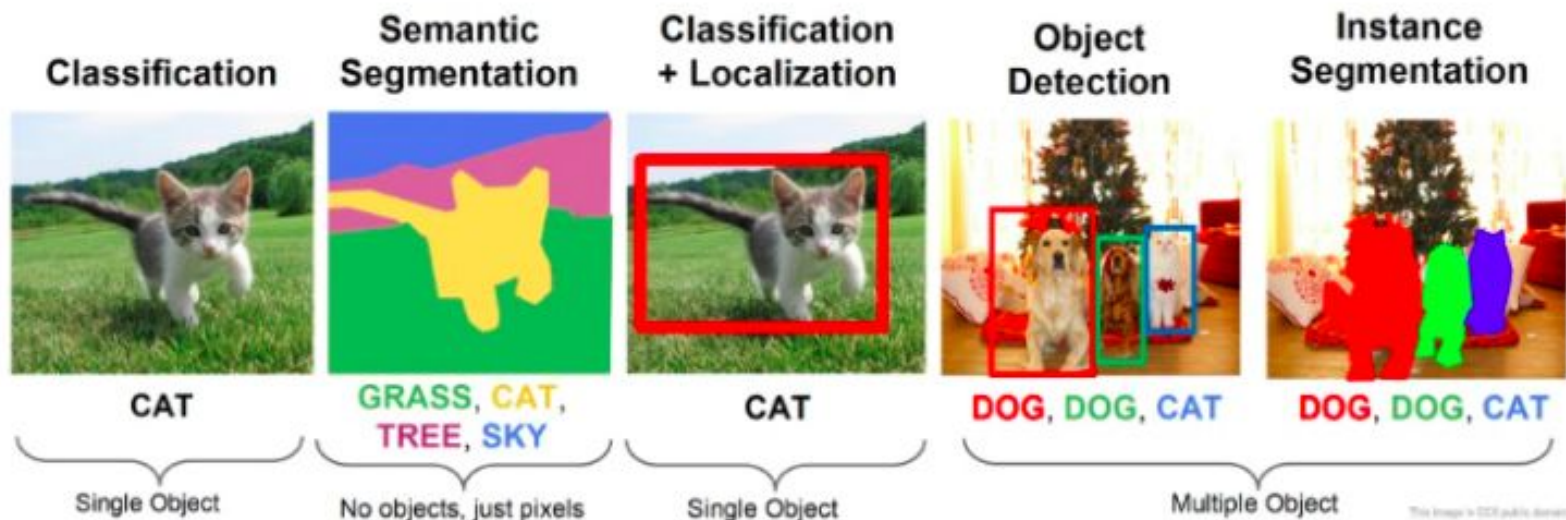
### B. Regression predictive modeling:

is the task of approximating a mapping function ( $f$ ) from input variables ( $X$ ) to a continuous output variable ( $y$ ). A continuous output variable is a real-value, such as an integer or floating point value. These are often quantities, such as amounts and sizes. A regression predictive model predicts a quantity, therefore to evaluate the model we report an error in those predictions.



## 2. Define the task

### Computer Vision Tasks



[http://cs231n.stanford.edu/slides/2017/cs231n\\_2017\\_lecture11.pdf](http://cs231n.stanford.edu/slides/2017/cs231n_2017_lecture11.pdf)

Figure 1: Different computer vision tasks. Source: Introduction to Artificial Intelligence and Computer Vision Revolution ([https://www.slideshare.net/darian\\_f/introduction-to-the-artificial-intelligence-and-computer-vision-revolution](https://www.slideshare.net/darian_f/introduction-to-the-artificial-intelligence-and-computer-vision-revolution)).



# 3. Choose your Network Architecture

- Image related tasks:
  - Convolutional Neural Networks (CNN)
- Time-series tasks:
  - Recurrent Neural Networks (RNN)
- Video/Audio related tasks:
  - (?)

# 3. Choose your Network Architecture

- Image related tasks:
  - Convolutional Neural Networks (CNN)
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  - Recurrent Neural Networks (RNN)
- Video/Audio related tasks:
  - (?)

Many architectures have been proposed in the literature.  
Look for what suits your problem

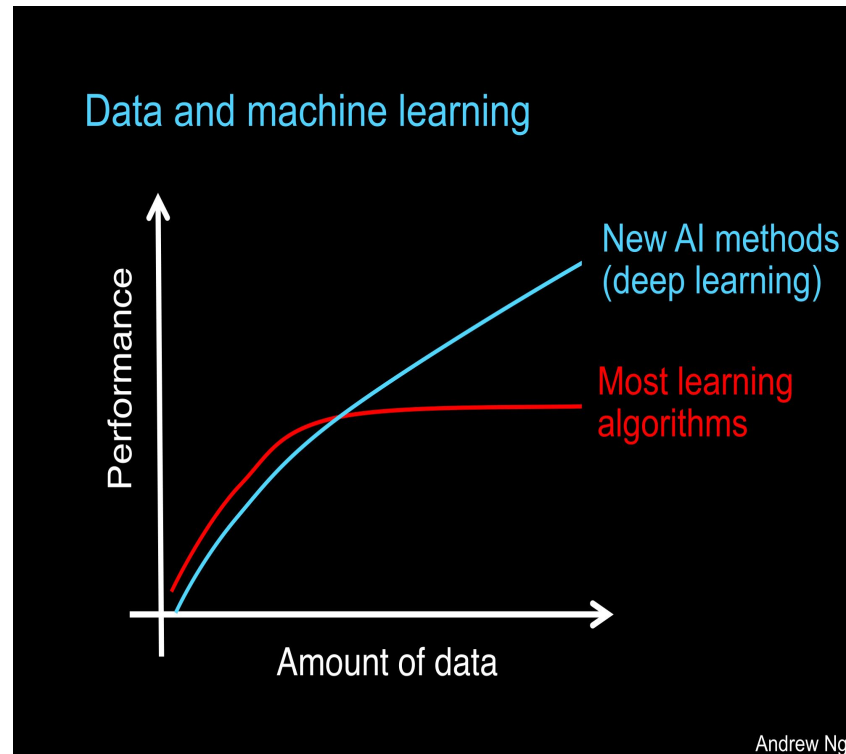
Don't Reinvent



Perfect It

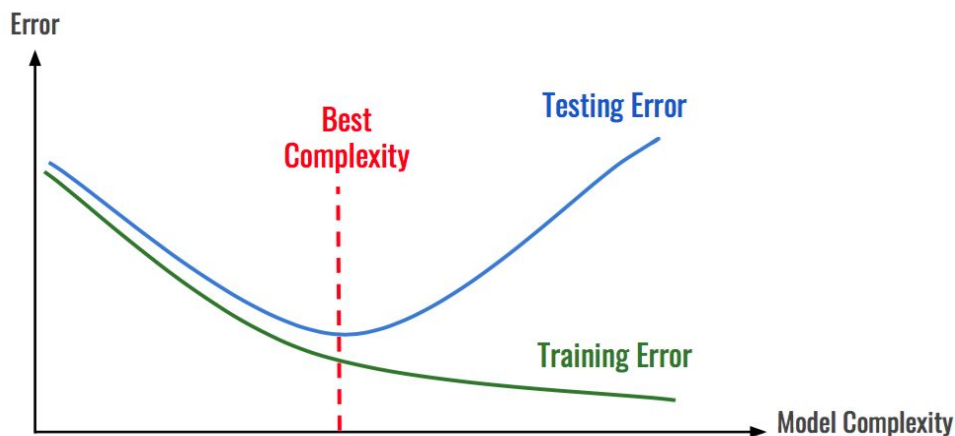
# 3. Choose your Network Architecture

- **Design choices:**
- **Transfer Learning** is a machine learning technique where a model trained on one task is re-purposed on a second related task.
- **Data Augmentation** is the technique of increasing the size of data used for training a model.



## 4. Start training ...

- Observe the progress of your training.
- Tune Hyperparameters.
  - Learning Rate
  - Number of epochs
- Test and evaluate your model.
- Don't fall into an overfitting case!



## Existing Platforms

PYTORCH

 Microsoft  
CNTK

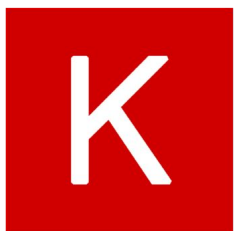
theano



Keras



TensorFlow



# Keras

Keras is a high-level neural networks API, written in Python and capable of running on top of TensorFlow, CNTK, or Theano. It was developed with a focus on enabling fast experimentation.

- Allows for easy and fast prototyping (through user friendliness, modularity, and extensibility).
- Supports both **convolutional networks** and **recurrent networks**, as well as combinations of the two.

[[keras.io](https://keras.io)]

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# Sequential Model

The **Sequential** model is a linear stack of layers.

You can create a **Sequential** model by passing a list of layer instances to the constructor:

```
from keras.models import Sequential
from keras.layers import Dense

model = Sequential([
    Dense(32, input_shape=(784,), activation='relu'),
    Dense(10, activation='softmax')
])
```

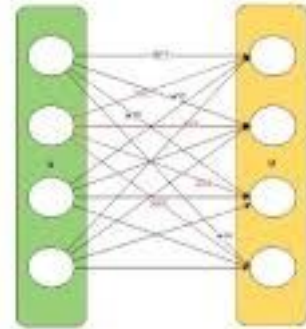
```
from keras.models import Sequential
model = Sequential()
```

# from keras import layers

- Core layers:
  - Dense layer: fully connected layer

```
model.add(Dense(4, activation='softmax'))
```

## Fully-connected layer





# from keras import layers

- Convolutional layers:
  - Conv1D, Conv2D, Conv3D
  - UpSampling1D, UpSampling2D...

1 <sub>x1</sub>	1 <sub>x0</sub>	1 <sub>x1</sub>	0	0
0 <sub>x0</sub>	1 <sub>x1</sub>	1 <sub>x0</sub>	1	0
0 <sub>x1</sub>	0 <sub>x0</sub>	1 <sub>x1</sub>	1	1
0	0	1	1	0
0	1	1	0	0

Image

4		

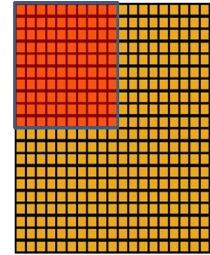
Convolved  
Feature

```
model.add(Conv2D(filters=5, kernel_size=(3,3), activation='sigmoid'))
```

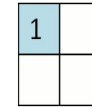
# from keras import layers

- Pooling Layers:
  - MaxPooling1D, MaxPooling2D, ...
  - AveragePooling1D, AveragePooling2D, ...

```
model.add(MaxPooling2D(pool_size=(8,8)))
```



Convolved  
feature



Pooled  
feature

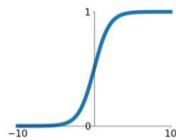


# from keras.layers import activations

Activation layers in neural networks, takes a value that is passed through a function which *squashes* the value into a range.

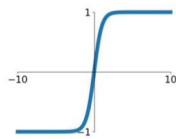
**Sigmoid**

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



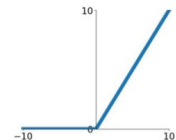
**tanh**

$$\tanh(x)$$



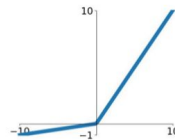
**ReLU**

$$\max(0, x)$$



**Leaky ReLU**

$$\max(0.1x, x)$$

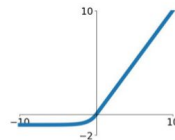


**Maxout**

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

**ELU**

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



# from keras.layers import activations

## Softmax

- calculates the probabilities of each target class over all possible target classes.
- is often used in the final layer of a neural network-based classifier.

$$\sigma(z)_j = \frac{e^{z_j}}{\sum_{k=1}^K e^{z_k}}$$

```
model.add(Activation('softmax'))
```

## Sigmoid

- returns a real-valued output.
- is often used as the activation function for artificial neurons.

$$\text{sigmoid}(x) = \frac{1}{1 + e^{-x}}$$

```
model.add(Activation('sigmoid'))
```

# from keras import losses

A **loss function** or **cost function** is a function that maps values of one or more variables onto a real number intuitively representing some associated "cost". An optimization problem seeks to minimize a loss function.

The loss function lets us quantify the quality of any particular set of parameters (weights **W** and biases **B**). Some available loss functions:

- `mean_squared_error`
- `mean_absolute_error`
- ...
- `categorical_crossentropy`
- `binary_crossentropy`
- ...

# from keras import optimizers

The goal of optimization is to find the set of parameters (**W** and **B**) that minimizes the loss function.

Some available optimizer:

- **SGD** #Stochastic gradient descent optimizer.
- **AdaGrad** #Adaptive gradient descent optimizer
- **RMSProp**
- **Adam** #adaptive moment estimation
- ...

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Algorithm	Gradient Descent
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$$\mathbf{g}_t \leftarrow \nabla_{\theta_{t-1}} f(\theta_{t-1})$$

$$\theta_t \leftarrow \theta_{t-1} - \eta \mathbf{g}_t$$

---

# from keras import optimizers

The goal of optimization is to find the set of parameters (**W** and **B**) that minimizes the loss function.

Some available optimizer:

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- ...

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Algorithm	Classical Momentum
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$$\mathbf{g}_t \leftarrow \nabla_{\theta_{t-1}} f(\theta_{t-1})$$

$$\mathbf{m}_t \leftarrow \mu \mathbf{m}_{t-1} + \mathbf{g}_t$$

$$\theta_t \leftarrow \theta_{t-1} - \eta \mathbf{m}_t$$

---

# from keras import optimizers

The goal of optimization is to find the set of parameters (**W** and **B**) that minimizes the loss function.

Some available optimizer:

- **SGD** #Stochastic gradient descent optimizer.
- **AdaGrad** #Adaptive gradient descent optimizer
- **RMSProp**
- **Adam** #adaptive moment estimation
- ...

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Algorithm	AdaGrad
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$$\mathbf{g}_t \leftarrow \nabla_{\theta_{t-1}} f(\theta_{t-1})$$

$$\mathbf{n}_t \leftarrow \mathbf{n}_{t-1} + \mathbf{g}_t^2$$

$$\theta_t \leftarrow \theta_{t-1} - \eta \frac{\mathbf{g}_t}{\sqrt{\mathbf{n}_t + \epsilon}}$$

---



# from keras import optimizers

The goal of optimization is to find the set of parameters (**W** and **B**) that minimizes the loss function.

Some available optimizer:

- **SGD** #Stochastic gradient descent optimizer.
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- **RMSProp**
- **Adam** #adaptive moment estimation
- ...

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**Algorithm** RMSProp

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$$\mathbf{g}_t \leftarrow \nabla_{\theta_{t-1}} f(\theta_{t-1})$$

$$\mathbf{n}_t \leftarrow v\mathbf{n}_{t-1} + (1-v)\mathbf{g}_t^2$$

$$\theta_t \leftarrow \theta_{t-1} - \eta \frac{\mathbf{g}_t}{\sqrt{\mathbf{n}_t + \epsilon}}$$

---

# from keras import optimizers

The goal of optimization is to find the set of parameters (**W** and **B**) that minimizes the loss function.

Some available optimizer:

- **SGD** #Stochastic gradient descent optimizer.
- **AdaGrad** #Adaptive gradient descent optimizer
- **RMSProp**
- **Adam** #adaptive moment estimation
- ...

---

**Algorithm Adam**

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$$\mathbf{g}_t \leftarrow \nabla_{\theta_{t-1}} f(\theta_{t-1})$$

$$\mathbf{m}_t \leftarrow \mu \mathbf{m}_{t-1} + (1 - \mu) \mathbf{g}_t$$

$$\hat{\mathbf{m}}_t \leftarrow \frac{\mathbf{m}_t}{1 - \mu^t}$$

$$\mathbf{n}_t \leftarrow \nu \mathbf{n}_{t-1} + (1 - \nu) \mathbf{g}_t^2$$

$$\hat{\mathbf{n}}_t \leftarrow \frac{\mathbf{n}_t}{1 - \nu^t}$$

$$\theta_t \leftarrow \theta_{t-1} - \eta \frac{\hat{\mathbf{m}}_t}{\sqrt{\hat{\mathbf{n}}_t + \epsilon}}$$

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# from keras import applications

Keras Applications are deep learning models that are made available alongside pre-trained weights. These models can be used for prediction, feature extraction, and fine-tuning.

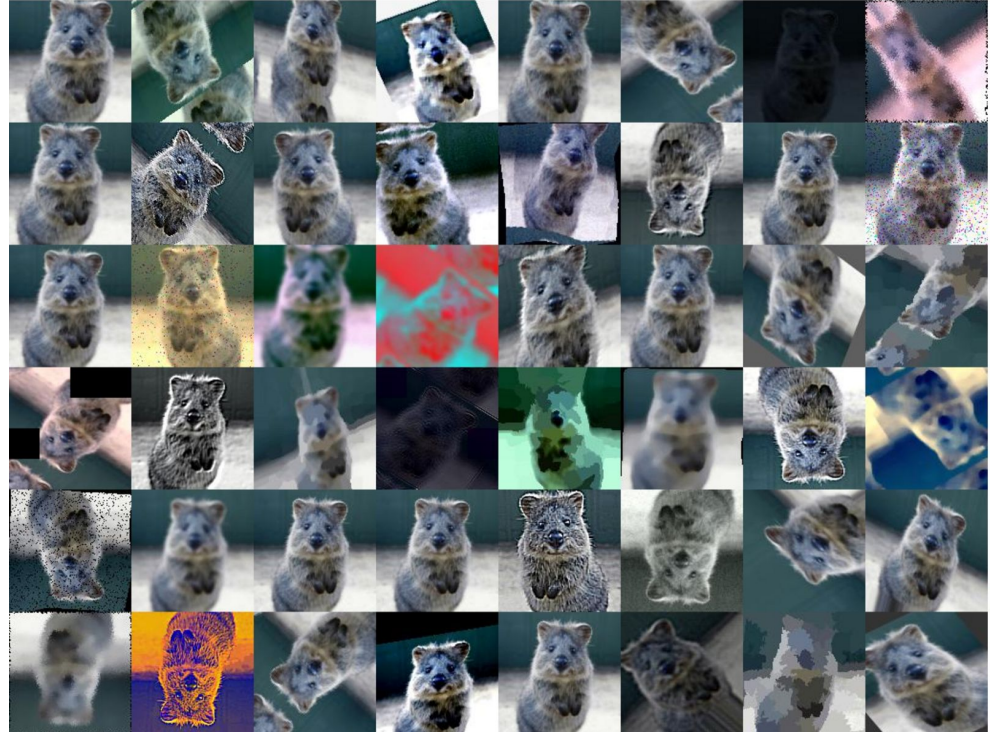
- Xception
- VGG16
- VGG19
- ResNet50
- InceptionV3
- InceptionResNetV2
- MobileNet
- DenseNet
- NASNet

```
from keras.applications.vgg16 import VGG16
```

```
model = VGG16(weights='imagenet', include_top=True)
```

# from `keras import data augmentation`

Image Augmentation is the process of taking images that are already in a training dataset and manipulating them to create many altered versions of the same image.



# from keras import data augmentation

Generate batches of tensor image data with real-time data augmentation. The data will be looped over (in batches) indefinitely.

```
datagen = ImageDataGenerator(  
    featurewise_std_normalization=True,  
    rotation_range=20,  
    width_shift_range=0.2,  
    height_shift_range=0.2,  
    horizontal_flip=True)  
  
datagen.fit(x_train)  
  
for x, y in datagen.flow(x_train, y_train, batch_size=32):  
    ...
```

# from keras import wrap-up!

```
model = Sequential()
model.add(Dense(32, input_dim=784))
model.add(Activation(sigmoid))

opt = Adam(lr=0.01)
model.compile(loss='categorical_crossentropy',
              optimizer=opt,
              metrics=['accuracy'])

model.fit(x_train, y_train,
         epochs=20,
         batch_size=32)
score = model.evaluate(x_test, y_test, batch_size=32)
```

# Exercise: handwritten digits

label = 5



label = 0



label = 4



label = 1



label = 9



label = 2



label = 1



label = 3



label = 1



label = 4



label = 3



label = 5



label = 3



label = 6



label = 1



label = 7



label = 2



label = 8



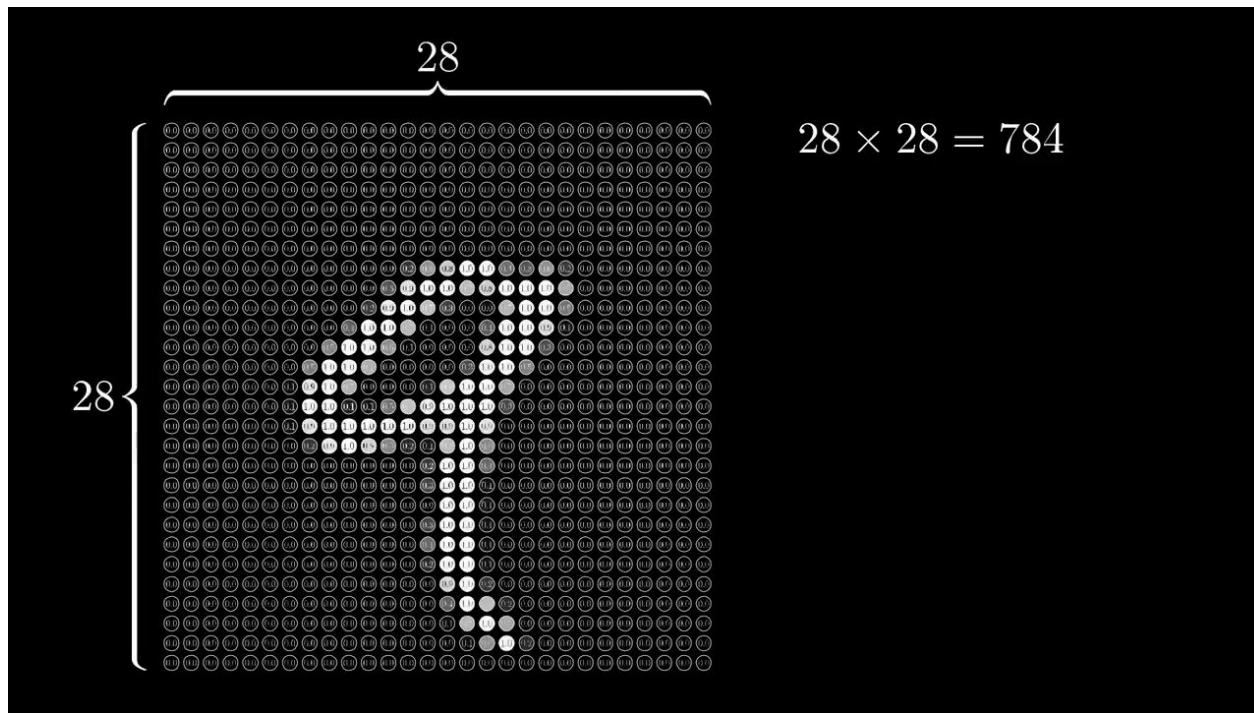
label = 6



label = 9

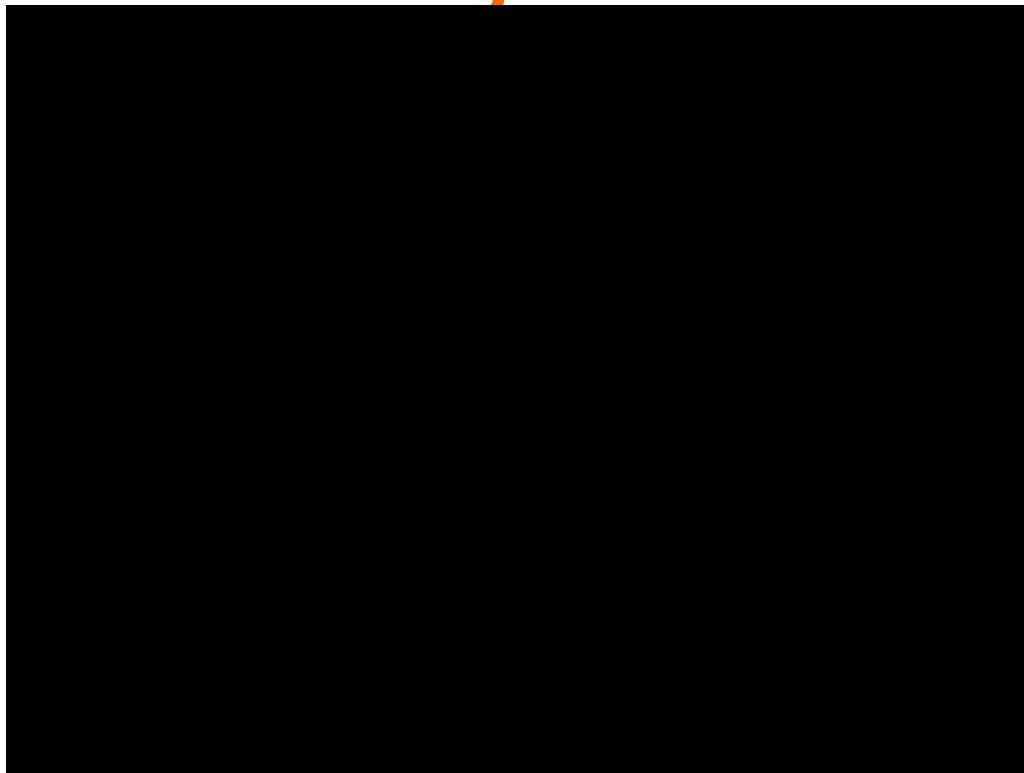


# Exercise: handwritten digits





# Exercise: handwritten digits



# Useful links:

Conda: <https://docs.conda.io/en/latest/miniconda.html>

Install keras: <https://anaconda.org/conda-forge/keras>

Keras Docs: <https://keras.io/>

MNIST dataset: <http://yann.lecun.com/exdb/mnist/>

If you have any question, feel free to contact me

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